

Hierarchical Fine-Grained Image Forgery Detection and Localization

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Abstract

Differences in forgery attributes of images generated in CNN-synthesized and image-editing domains are large, and such differences make a unified image forgery detection and localization (IFDL) challenging. To this end, we present a hierarchical fine-grained formulation for IFDL representation learning. Specifically, we first represent forgery attributes of a manipulated image with multiple labels at different levels. Then we perform fine-grained classification at these levels using the hierarchical dependency between them. As a result, the algorithm is encouraged to learn both comprehensive features and inherent hierarchical nature of different forgery attributes, thereby improving the IFDL representation. Our proposed IFDL framework contains three components: multi-branch feature extractor, localization and classification modules. Each branch of the feature extractor learns to classify forgery attributes at one level, while localization and classification modules segment the pixel-level forgery region and detect image-level forgery, respectively. Lastly, we construct a hierarchical fine-grained dataset to facilitate our study. We demonstrate the effectiveness of our method on 7 different benchmarks, for both tasks of IFDL and forgery attribute classification. Our source code and dataset can be found: github.com/CHELSEA234/HiFi-IFDL.

1. Introduction

Chaotic and pervasive multimedia information sharing offers better means for spreading misinformation [1], and the forged image content could, in principle, sustain recent “infodemics” [3]. Firstly, CNN-synthesized images made extraordinary leaps culminating in recent synthesis methods—Dall·E [52] or Google ImageN [57]—based on diffusion models (DDPM) [24], which even generates realistic videos from text [23, 60]. Secondly, the availability of image editing toolkits produced a substantially low-cost access to image forgery or tampering (e.g., splicing and inpainting). In response to such an issue of image forgery, the computer vision community has made considerable ef-

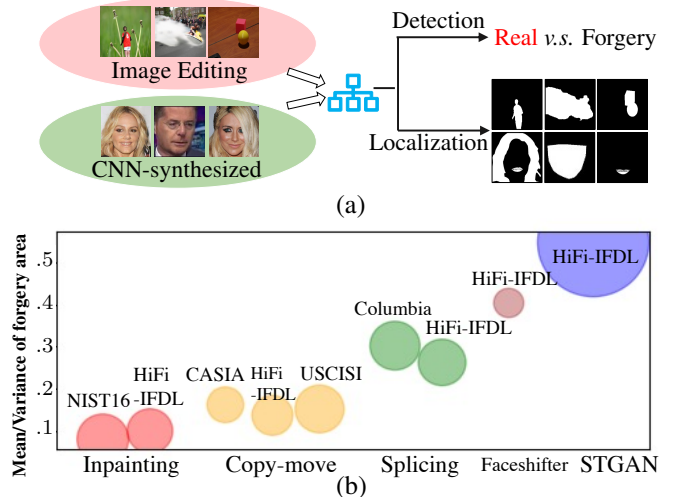


Figure 1. (a) In this work, we study image forgery detection and localization (IFDL), regardless of forgery method domains. (b) The distribution of forgery region depends on individual forgery methods. Each color represents one forgery category (x-axis). Each bubble represents one image forgery dataset. The y-axis denotes the average of forgery area. The bubble’s area is proportional to the variance of the forgery area.

orts, which however branch separately into two directions: detecting either CNN synthesis [62, 64, 73], or conventional image editing [17, 26, 43, 63, 68]. As a result, these methods may be ineffective when deploying to real-life scenarios, where forged images can possibly be generated from either CNN-synthesized or image-editing domains.

To push the frontier of image forensics [59], we study the image forgery detection and localization problem (IFDL)—Fig. 1a—regardless of the forgery method domains, i.e., CNN-synthesized or image editing. It is challenging to develop a unified algorithm for two domains, as images, generated by different forgery methods, differ largely from each other in terms of various forgery attributes. For example, a forgery attribute can indicate whether a forged image is fully synthesized or partially manipulated, or whether the forgery method used is the diffusion model generating im-

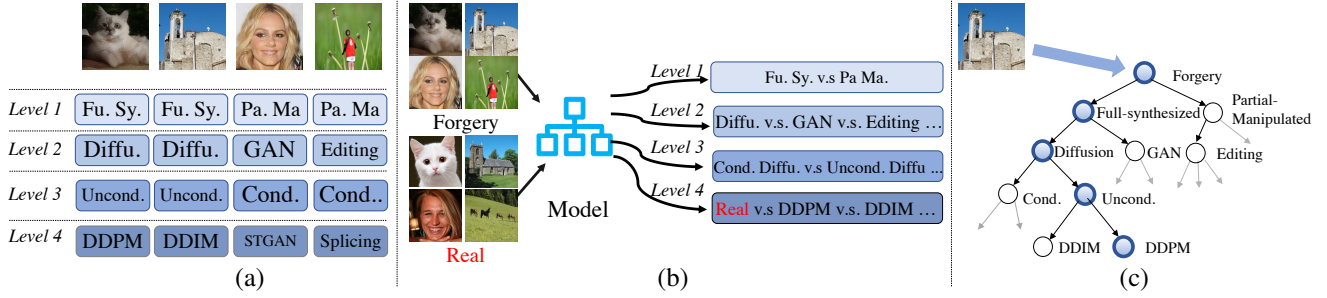


Figure 2. (a) We represent the forgery attribute of each manipulated image with multiple labels, at different levels. (b) For an input image, we encourage the algorithm to classify its fine-grained forgery attributes at different levels, *i.e.* a 2-way classification (fully synthesized or partially manipulated) on level 1. (c) We perform the fine-grained classification via the hierarchical nature of different forgery attributes, where each depth l node’s classification probability is conditioned on classification probabilities of neighbor nodes at depth $(l - 1)$. [Key: Fu. Sy.: Fully Synthesized; Pa. Ma.: Partially manipulated; Diffu.: Diffusion model; Cond.: Conditional; Uncond.: Unconditional].

ages from the Gaussian noise, or an image editing process that splices two images via Poisson editing [51]. Therefore, to model such complex forgery attributes, we first represent forgery attribute of each forged image with multiple labels at different levels. Then, we present a hierarchical fine-grained formulation for IFDL, which requires the algorithm to classify fine-grained forgery attributes of each image at different levels, via the inherent hierarchical nature of different forgery attributes.

Fig. 2a shows the interpretation of the forgery attribute with a hierarchy, which evolves from the general forgery attribute, fully-synthesized vs partial-manipulated, to specific individual forgery methods, such as DDPM [24] and DDIM [61]. Then, given an input image, our method performs fine-grained forgery attribute classification at different levels (see Fig. 2b). The image-level forgery detection benefits from this hierarchy as the fine-grained classification learns the comprehensive IFDL representation to differentiate individual forgery methods. Also, for the pixel-level localization, the fine-grained classification features can serve as a prior to improve the localization. This holds since the distribution of the forgery area is prominently correlated with forgery methods, as depicted in Fig. 1b.

In Fig. 2c, we leverage the hierarchical dependency between forgery attributes in fine-grained classification. Each node’s classification probability is conditioned on the path from the root to itself. For example, the classification probability at a node of DDPM is conditioned on the classification probability of all nodes in the path of Forgery \rightarrow Fully Synthesis \rightarrow Diffusion \rightarrow Unconditional \rightarrow DDPM. This differs to prior work [44, 45, 68, 71] which assume a “flat” structure in which attributes are mutually exclusive. Predicting the entire hierarchical path helps understanding forgery attributes from the coarse to fine, thereby capturing dependencies among individual forgery attributes.

To this end, we propose Hierarchical Fine-grained Network (HiFi-Net). HiFi-Net has three components: multi-branch feature extractor, localization module and detection

module. Each branch of the multi-branch extractor classifies images at one forgery attribute level. The localization module generates the forgery mask with the help of a deep-metric learning based objective, which improves the separation between real and forged pixels. The classification module first overlays the forgery mask with the input image and obtain a masked image where only forged pixels remain. Then, we use partial convolution to process masked images, which further helps learn IFDL representations.

Lastly, to facilitate our study of the hierarchical fine-grained formulation, we construct a new dataset, termed Hierarchical Fine-grained (HiFi) IFDL dataset. It contains 13 forgery methods, which are either latest CNN-synthesized methods or representative image editing methods. HiFi-IFDL dataset also induces a hierarchical structure on forgery categories to enable learning a classifier for various forgery attributes. Each forged image is also paired with a high-resolution ground truth forgery mask for the localization task. In summary, our contributions are as follows:

- ◊ We study the task of image forgery detection and localization (IFDL) for both image editing and CNN-synthesized domains. We propose a hierarchical fine-grained formulation to learn a comprehensive representation for IFDL and forgery attribute classification.

- ◊ We propose a IFDL algorithm, named HiFi-Net, which not only performs well on forgery detection and localization, also identifies a diverse spectrum of forgery attributes.

- ◊ We construct a new dataset (HiFi-IFDL) to facilitate the hierarchical fine-grained IFDL study. When evaluating on 7 benchmarks, our method outperforms the state of the art (SoTA) on the tasks of IFDL, and achieve a competitive performance on the forgery attribute classifications.

2. Related Work

Image Forgery Detection. In the generic image forgery detection, it is required to distinguish real images from ones generated by a CNN: Zhang *et al.* [73] report that it is difficult for classifiers to generalize across different GANs

Method	Det.	Loc.	Forgery Type	Attribute Learning
Wu <i>et al.</i> [68]	✗	✓	Editing	✗
Hu <i>et al.</i> [26]	✗	✓	Editing	✗
Liu <i>et al.</i> [43]	✓	✓	Editing	✗
Dong <i>et al.</i> [17]	✓	✓	Editing	✗
Wang <i>et al.</i> [63]	✓	✓	Editing	✗
Zhang <i>et al.</i> [73]	✓	✗	CNN-based	✗
Wang <i>et al.</i> [64]	✓	✗	CNN-based	✗
Asnani <i>et al.</i> [6]	✓	✗	CNN-based	syn.-based
Yu <i>et al.</i> [71]	✓	✗	CNN-based	syn.-based
Stehouwer <i>et al.</i> [62]	✓	✓	CNN-based	✗
Huang <i>et al.</i> [27]	✓	✓	CNN-based	✗
Ours	✓	✓	Both types	for.-based

Table 1. Comparison to previous works. [Key: Det.: detection, Loc.: localization, Syn.: synthesis, for.: forgery]

and leverage upsampling artifacts as a strong discriminator for GAN detection. On the contrary, against expectation, the work by Wang *et al.* [64] shows that a baseline classifier *can* actually generalize in detecting different GAN models contingent to being trained on synthesized images from ProGAN [29]. Another thread is facial forgery detection [5, 8, 15, 16, 19, 28, 34, 38, 55], and its application in bio-metrics [4, 20–22, 25]. All these works specialize in the image-level forgery detection, which however does not meet the need of knowing where the forgery occurs on the pixel level. Therefore, we perform both image forgery detection and localization, as reported in Tab. 1.

Forgery Localization. Most of existing methods perform pixel-wise classification to identify forged regions [26, 63, 68] while early ones use a region [76] or patch-based [47] approach. The idea of localizing forgery is also adopted in the DeepFake Detection community by segmenting the artifacts in facial images [10, 14, 74]. Zhou *et al.* [75] improve the localization by focusing on object boundary artifacts. The MVSS-Net [11, 17] uses multi-level supervision to balance between sensitivity and specificity. MaLP [7] shows that the proactive scheme benefits both detection and localization. While prior methods are restricted to one domain, our method unifies across different domains.

Attribute Learning. CNN-synthesized image attributes can be observed in the frequency domain [64, 73], where different GAN generation methods have distinct high-frequency patterns. The task of “GAN discovery and attribution” attempts to identify the exact generative model [44, 45, 71] while “model parsing” identifies both the model and the objective function [6]. These works differ from ours in two aspects. Firstly, the prior work concentrates the attribute used in the digital synthesis method (synthesis-based), yet our work studies forgery-based attribute, *i.e.*, to classify GAN-based fully-synthesized or partial manipulation from the image editing process. Secondly, unlike the prior work that assumes a “flat” structure between different attributes, we represent all forgery attributes in a hierarchical way, exploring dependencies among them.

3. HiFi-Net

In this section, we introduce HiFi-Net as shown in Fig. 3. We first define the image forgery detection and localization (IFDL) task and hierarchical fine-grained formulation. In IFDL, an image $\mathbf{X} \in \mathbb{R}_{[0,255]}^{3 \times W \times H}$ is mapped to a binary variable \mathbf{y} for image-level forgery detection and a binary mask $\mathbf{M} \in \mathbb{R}_{[0,1]}^{W \times H}$ for localization, where the \mathbf{M}_{ij} indicates if the ij -th pixel is manipulated or not.

In the hierarchical fine-grained formulation, we train the given IFDL algorithm towards fine-grained classifications, and in the inference we evaluate the binary classification results on the image-level forgery detection. Specifically, we denote a categorical variable $\hat{\mathbf{y}}_b$ at branch b , where its value depends on which level we conduct the fine-grained forgery attribute classification. For example, as depicted in Fig. 2b, two categories at level 1 are full-synthesized, partial-manipulated; four classes at level 2 are diffusion model, GAN-based method, image editing, CNN-based partial-manipulated method; classes at level 3 discriminate whether forgery methods are conditional or unconditional; 14 classes at level 4 are real and 13 specific forgery methods. We detail this in Sec. 4 and Fig. 6a.

To this end, we propose HiFi-Net (Fig. 3) which consists of a multi-branch feature extractor (Sec. 3.1) that performs fine-grained classifications at different specific forgery attribute levels, and two modules (Sec. 3.2 and Sec. 3.3) that help the forgery localization and detection, respectively. Lastly, Sec. 3.4 introduces training procedure and inference.

3.1. Multi-Branch Feature Extractor

We first extract feature of the given input image via the color and frequency blocks, and this frequency block applies a Laplacian of Gaussian (LoG) [9] onto the CNN feature map. This architecture design is similar to the method in [46], which exploits image generation artifacts that can exist in both RGB and frequency domain [17, 63, 64, 73].

Then, we propose a multi-branch feature extractor, and whose branch is denoted as θ_b with $b \in \{1 \dots 4\}$. Specifically, each θ_b generates the feature map of a specific resolution, and such a feature map helps θ_b conduct the fine-grained classification at the corresponding level. For example, for the finest level (*i.e.* identifying the individual forgery methods), one needs to model contents at all spatial locations, which requires high-resolution feature map. In contrast, it is reasonable to have low resolution feature maps for the coarsest level (*i.e.* binary) classification.

We observe that different forgery methods generate manipulated areas with different distributions (Fig. 1b), and different patterns, *e.g.*, deepfake methods [37, 55] manipulate the whole inner part of the face, whereas STGAN [42] changes sparse facial attributes such as mouth and eyes. Therefore, we place the localization module at the end of

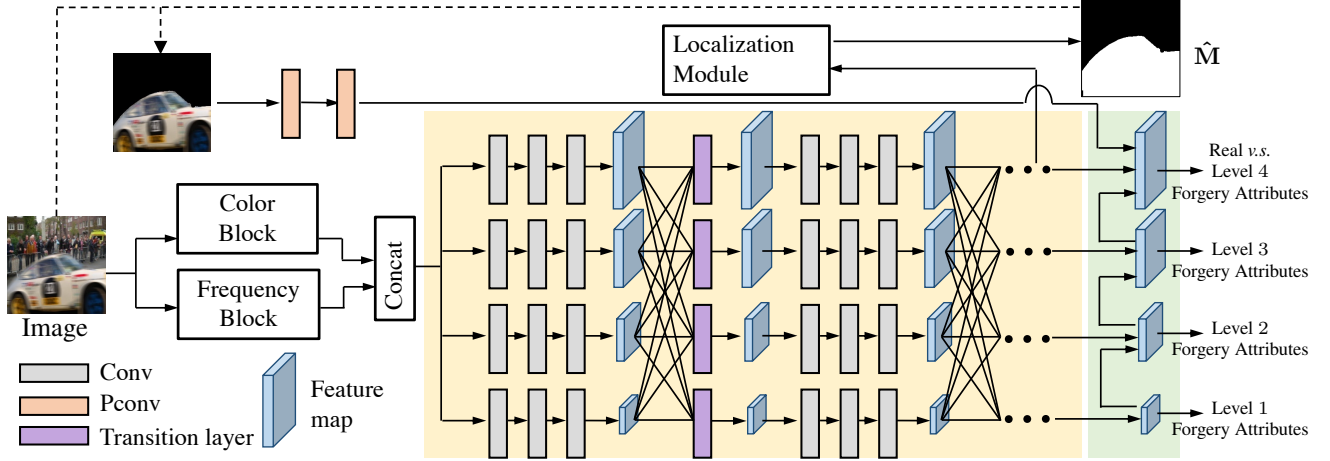


Figure 3. Given the input image, we first leverage color and frequency blocks to extract features. The multi-branch feature extractor (yellow) learns feature maps of different resolutions, for the fine-grained classification at different levels. The localization module (Sec. 3.2) generates the forgery mask, \hat{M} , to identify the manipulation region. After that, we use the partial convolution (PConv) layer to encode the masked image (Eq. 2), and then leverage such “masked” embeddings in the classification module (green), which details in Sec. 3.3.

the highest-resolution branch of the extractor—the branch to classify specific forgery methods. In this way, features for fine-grained classification serve as a prior for localization. It is important to have such a design for localizing both manipulated images with CNNs or classic image editing.

3.2. Localization Module

Architecture. The localization module maps feature output from the highest-resolution branch (θ_4), denoted as $\mathbf{F} \in \mathbb{R}^{512 \times W \times H}$, to the mask \hat{M} to localize the forgery. To model the dependency and interactions of pixels on the large spatial area, the localization module employs the self-attention mechanism [65, 72]. As shown in the localization module architecture in Fig. 4, we use 1×1 convolution to form g , ϕ and ψ , which convert input feature \mathbf{F} into $\mathbf{F}_g = g(\mathbf{F})$, $\mathbf{F}_\phi = \phi(\mathbf{F})$ and $\mathbf{F}_\psi = \psi(\mathbf{F})$. Given \mathbf{F}_ϕ and \mathbf{F}_θ , we compute the spatial attention matrix $\mathbf{A}_s = \text{softmax}(\mathbf{F}_\phi^T \mathbf{F}_\theta)$. We then use this transformation \mathbf{A}_s to map \mathbf{F}_g into a global feature map $\mathbf{F}' = \mathbf{A}_s \mathbf{F}_g \in \mathbb{R}^{512 \times W \times H}$.

Objective Function. Following [46], we employ a metric learning objective function for localization, which creates a wider margin between real and manipulated pixels. We firstly learn features of each pixel, and then model the geometry of such learned features with a radial decision boundary in the hyper-sphere. Specifically, we start with pre-computing a reference center $\mathbf{c} \in \mathbb{R}^D$, by averaging the features of all pixels in real images of the training set. We use $\mathbf{F}'_{ij} \in \mathbb{R}^D$ to indicate the ij -th pixel of the final mask prediction layer. Therefore, our localization loss \mathcal{L}_{loc} is:

$$\mathcal{L}_{loc} = \frac{1}{HW} \sum_i^H \sum_j^W \mathcal{L}(\mathbf{F}'_{ij}, \mathbf{M}_{ij}; \mathbf{c}, \tau), \quad (1)$$

where:

$$\mathcal{L} = \begin{cases} \|\mathbf{F}'_{ij} - \mathbf{c}\|_2 & \text{if } \mathbf{M}_{ij} \text{ real} \\ \max(0, \tau - \|\mathbf{F}'_{ij} - \mathbf{c}\|_2) & \text{if } \mathbf{M}_{ij} \text{ forged.} \end{cases}$$

Here τ is a pre-defined margin. The first term in \mathcal{L} improves the feature space compactness of real pixels. The second term encourages the distribution of forged pixels to be far away from real by a margin τ . Note our method differs to [46, 56] in two aspects: 1) unlike [56], we use the second term in \mathcal{L} to enforce separation; 2) compared to the image-level loss in [46] that has two margins, we work on the more challenging pixel-level learning. Thus we use a single margin, which reduces the number of hyper-parameters and improve the simplicity.

3.3. Classification Module

Partial Convolution. Unlike prior work [17, 26, 63] whose ultimate goal is to localize the forgery mask, we reuse the forgery mask to help HiFi-Net learn the optimal feature for classifying fine-grained forged attributes. Specifically, we generate a binary mask \hat{M} , then overlay \hat{M} with the input image as $\mathbf{X} \odot \hat{M}$ to obtain the masked image $\mathbf{X}_{mask} \in \mathbb{R}^{3 \times W_0 \times H_0}$. To process the masked image, we resort to the *partial convolution* operator (PConv) [41], whose convolution kernel is renormalized to be applied only on unmasked pixels. The idea is to have feature maps only describe pixels at the manipulated region. PConv acts as conditioned dot product for each kernel, conditioned on the mask. Denoting \mathbf{W}_{par} as the convolution kernel, we have:

$$\mathbf{X}'_{mask} = \mathbf{W}_{par}^T \mathbf{X}_{mask} = \mathbf{W}_{par}^T (\mathbf{X} \odot \hat{M}), \quad (2)$$

where the dot product \odot is “renormalized” to account for zeros in the mask. At different layers, we update and propa-

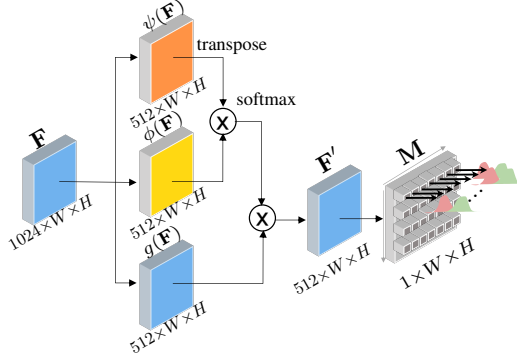


Figure 4. The localization module adopts the self-attention mechanism to transfer the feature map \mathbf{F} to the localization mask \mathbf{M} .

gate the new mask $\hat{\mathbf{M}}'$ according to the following equation:

$$\hat{\mathbf{M}}' = \begin{cases} 1 & \text{If } \|\hat{\mathbf{M}}\| \geq 0 \\ 0 & \text{otherwise.} \end{cases} \quad (3)$$

Specifically, \mathbf{X}_{mask} represents the most prominent forged image region. We believe the feature of \mathbf{X}_{mask} can serve as a prior for HiFi-Net, to better learn the attribute of individual forgery methods. For example, the observation whether the forgery occurs on the eyebrow or entire face, helps decide whether given images are manipulated by STGAN [42] or FaceShifter [37]. The localization part is implemented with only two light-weight partial convolutional layers for higher efficiency.

Hierarchical Path Prediction. We intend to learn the hierarchical dependency between different forgery attributes. Given the image \mathbf{X} , we denote output logits and predicted probability of the branch θ_b as $\theta_b(\mathbf{X})$ and $p(\mathbf{y}_b|\mathbf{X})$, respectively. Then, we have:

$$p(\mathbf{y}_b|\mathbf{X}) \doteq \text{softmax}(\theta_b(\mathbf{X}) \odot (1 + p(\mathbf{y}_{b-1}|\mathbf{X}))) \quad (4)$$

Before computing the probability $p(\mathbf{y}_b|\mathbf{X})$ at branch θ_b , we scale logits $\theta_b(\mathbf{X})$ based on the previous branch probability $p(\mathbf{y}_{b-1}|\mathbf{X})$. Then, we enforce the algorithm to learn hierarchical dependency. Specifically, in Eq. (4), we repeat the probability of the coarse level $b-1$ for all the logits output by branch at level b , following the hierarchical structure. Fig. 5 shows that the logits associated to predicting DDPM or DDIM are multiplied by probability for the image to be Unconditional (Diffusion) in the last level, according to the hierarchical tree structure.

3.4. Training and Inference

In the training, each branch is optimized towards the classification at the corresponding level, we use 4 classification losses, \mathcal{L}_{cls}^1 , \mathcal{L}_{cls}^2 , \mathcal{L}_{cls}^3 and \mathcal{L}_{cls}^4 for 4 branches. At the branch b , \mathcal{L}_{cls}^b is the cross entropy distance between $p(\mathbf{y}_b|\mathbf{X})$ and a ground truth categorical $\hat{\mathbf{y}}_b$. The architecture

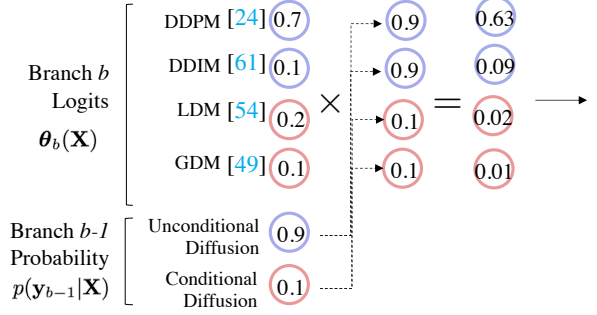


Figure 5. The classification probability output from branch θ_b depends on the predicted probability at branch θ_{b-1} , following the definition of the hierarchical forgery attributes tree.

is trained end-to-end with different learning rates per layers. The detailed objective function is:

$$\mathcal{L}_{tot} = \begin{cases} \lambda \mathcal{L}_{loc} + \mathcal{L}_{cls}^1 + \mathcal{L}_{cls}^2 + \mathcal{L}_{cls}^3 + \mathcal{L}_{cls}^4 & \text{if } \mathbf{X} \text{ is forged} \\ \lambda \mathcal{L}_{loc} + \mathcal{L}_{cls}^4 & \text{if } \mathbf{X} \text{ is real} \end{cases}$$

where \mathbf{X} is the input image. When the input image is labeled as “real”, we only apply the last branch (θ_4) loss function, otherwise we use all the branches. λ is the hyper-parameter that keeps \mathcal{L}_{loc} on a reasonable magnitude.

In the inference, HiFi-Net generates the forgery mask from the localization module, and predicts forgery attributes at different levels. We use the output probabilities at level 4 for forgery attribute classification. For binary “forged vs. real” classification, we predict as forged if the highest probability falls in any manipulation method at level 4.

4. Hierarchical Fine-grained IFDL dataset

We construct a fine-grained hierarchical benchmark, named HiFi-IFDL, to facilitate our study. HiFi-IFDL contains some most updated and representative forgery methods, for two reasons: 1) Image synthesis evolves into a more advanced era and artifacts become less prominent in the recent forgery method; 2) It is impossible to include all possible generative method categories, such as VAE [33] and face morphing [58]. So we only collect the most-studied forgery types (*i.e.*, splicing) and the most recent generative methods (*i.e.*, DDPM).

Specifically, HiFi-IFDL includes images generated from 13 forgery methods spanning from CNN-based manipulations to image editing, as shown in the taxonomy of Fig. 6a. Each forgery method generates 100,000 images. For the real images, we select them from 6 datasets (*e.g.*, FFHQ [32], AFHQ [12], CelebA HQ [36], Youtube face [55], MSCOCO [40], and LSUN [70]). We either take the entire real image datasets or select 100,000 images. Training, validation and test sets have 1,710K, 15K and 174K images. While there are different ways to design a forgery hierarchy, our hierarchy starts at the root of an image being forged, and

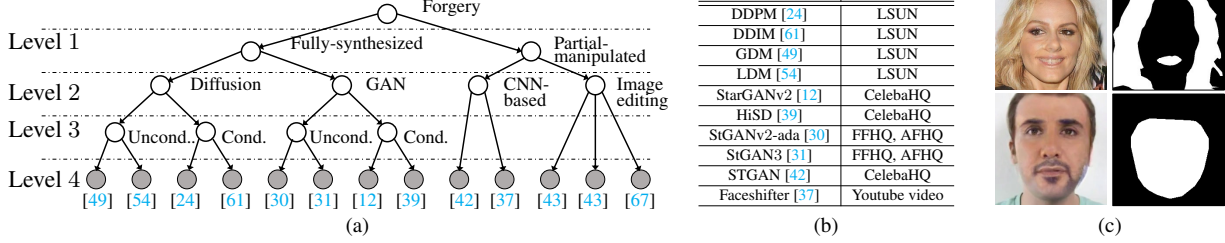


Figure 6. Overview of HiFi-IFDL dataset. (a) At level 1, we separate forged images into fully-synthesized and partial-manipulated. The second level discriminates different forgery methodologies, *e.g.*, image editing, CNN-based partial manipulation, Diffusion or GANs. Then, we separate images based on whether forgery methods are conditional or unconditional. The final level refers to the specific forgery method. (b) The table of forgery methods and images source that forgery methods are trained on. The dataset details can be found in the supplementary material. (c) We offer high resolution forgery masks on manipulated images.

then each level is made more and more specific to arrive at the actual generator. Our work studies *the impact of the hierarchical formulation to IFDL*. While different hierarchy definitions are possible, it is beyond the scope of this paper.

5. Experiments

We evaluate image forgery detection/localization (IFDL) on 7 datasets, and forgery attribute classification on HiFi-IFDL dataset. Our method is implemented on PyTorch and trained with 400,000 iterations, and batch size 16 with 8 real and 8 forged images. The details can be found in the supplementary.

5.1. Image Forgery Detection and Localization

5.1.1 HiFi-IFDL Dataset

Tab. 2 reports the different model performance on the HiFi-IFDL dataset, in which we use AUC and F1 score as metrics on both image-level forgery detection and pixel-level localization. Specifically, in Tab. 2a, first we observe that the pre-trained CNN-detector [64] does not perform well because it is trained on GAN-generated images that are different from images manipulated by diffusion models. Such differences can be seen in Fig. 2c, where we visualize the frequency domain artifacts, by following the routine [64] that applies the high-pass filter on the image generated by different forgery methods. Similar visualization is adopted in [13, 53, 64, 73] also. Then, we train both prior methods on HiFi-IFDL, and they again perform worse than our model: CNN-detector uses ordinary ResNet50, but our model is specifically designed for image forensics. Two-branch processes deepfakes video by LSTM that is less effective to detect forgery in image editing domain. Attention Xception [62] and PSCC [43] are proposed for facial image forgery and image editing domain, respectively. These two methods perform worse than us by 9.3% and 3.6% AUC, respectively. We believe this is because our method can leverage localization results to help the image-level detection.

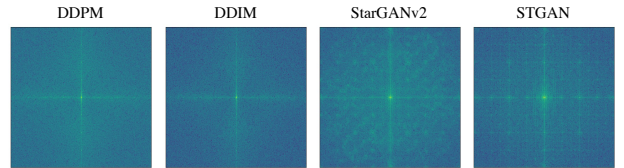
In Tab. 2b, we compare with previous methods which

Forgery Detection	CNN-syn.		Image Edit.		Overall	
	AUC	F1	AUC	F1	AUC	F1
CNN-det.* [64]	76.5	60.5	54.8	33.5	56.5	40.5
CNN-det. [64]	92.3	90.0	87.0	74.7	90.1	83.7
Two-bran. [46]	93.3	89.2	83.3	66.7	86.7	80.2
Att. Xce. [62]	93.8	91.2	90.8	82.1	87.3	90.0
PSCC [43]	94.6	93.2	90.7	82.3	93.2	91.3
Ours	97.0	96.1	91.5	85.9	96.8	94.1

(a) CNN-detector [64] has 4 variants with different augmentations, and we report the variant with the best performance. For Two-branch [46], we implement this method with the help of its authors.

Forgery Localization	CNN-syn.		Image Edit.		Overall	
	AUC	F1	AUC	F1	AUC	F1
OSN-det.* [69]	51.4	38.8	83.2	70.1	79.4	56.5
CatNet* [35]	48.6	31.9	86.1	79.4	78.3	65.1
CatNet [35]	92.5	81.5	92.0	88.2	92.4	86.8
Att. Xce. [62]	89.1	87.7	83.3	79.3	87.1	86.5
PSCC [43]	94.3	96.8	91.1	86.5	92.7	94.9
Ours	98.4	97.0	93.0	90.1	95.3	96.9

(b) OSN-det [69] only releases pre-trained weights with the inference script, without the training script.



(c) Frequency artifacts in different forgery methods. DDPM [24] and DDIM [61] do not exhibit the checkboard patterns [64, 73] observed in GAN-based methods, such as StarGAN-v2 [12] and STGAN [42].

Table 2. IFDL Results on HiFi-IFDL. * means we apply author-released pre-trained models. Models without * mean they are trained on HiFi-IFDL training set. **[Bold: best result]**.

can perform the forgery localization. Specifically, the pre-trained OSN-detector [69] and CatNet [35] do not work well on CNN-synthesized images in HiFi-IFDL dataset, since they merely train models on images manipulated by editing methods. Then, we use HiFi-IFDL dataset to train CatNet, but it still performs worse than ours: CatNet uses DCT stream to help localize area of splicing and copy-move, but

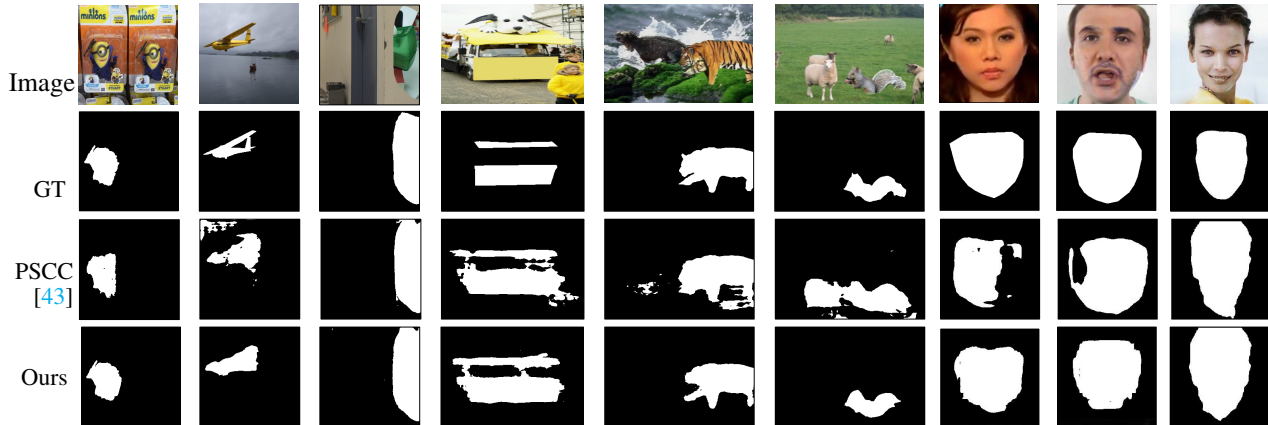


Figure 7. Qualitative results on different forged images. The first 6 columns are from image editing methods whereas the last 3 columns are images generated by Faceshifter [37] and STGAN [42].

Localization	Col.	Cov.	NI.16	CAS.	IM20	Avg.
<i>Metric: AUC(%) – Pre-trained</i>						
ManT. [68]	82.4	81.9	79.5	81.7	74.8	80.0
SPAN [26]	93.6	92.2	84.0	79.7	75.0	84.9
PSCC [43]	98.2	84.7	85.5	82.9	80.6	86.3
Ob.Fo. [63]	95.5	92.8	87.2	84.3	82.1	88.3
Ours*	98.3	93.2	87.0	85.8	82.9	89.4
Ours	98.4	92.4	86.9	86.6	83.4	89.6

(a)

Localization	Cov.	CAS.	NI.16	Avg.
<i>Metric: AUC(%) / F1(%) – Fine-tuned</i>				
SPAN [26]	93.7/55.8	83.8/40.8	96.1/58.2	91.2/51.6
PSCC [43]	94.1/72.3	87.5/55.4	99.6/81.9	93.7/69.8
Ob.Fo. [63]	95.7/75.8	88.2/57.9	99.6/82.4	94.5/72.0
Ours	96.1/80.1	88.5/61.6	98.9/85.0	94.6/75.5

(b)

Detection	AUC(%)	F1(%)
ManT. [68]	59.9	56.7
SPAN [26]	67.3	63.8
PSCC [43]	99.5	97.1
Ob.Fo. [63]	99.7	97.3
Ours	99.5	97.4

(c)

Table 3. IFDL results on the image editing. (a) Localization performance of the pre-train model. (b) Localization performance of the fine-tuned model. (c) Detection performance on CASIA dataset. All results of prior works are ported from [63]. [Key: **Best**; **Second Best**; Ours* uses the same pre-trained dataset as [43], and ours is pre-trained on HiFi-IFDL].

HiFi-IFDL contains more forgery types (*e.g.*, inpainting). Meanwhile, the accurate classification performance further helps the localization as statistics and patterns of forgery regions are related to different individual forgery method. For example, for the forgery localization, we achieve 2.6% AUC and 2.0% F1 improvement over PSCC. Additionally, the superior localization demonstrates that our hierarchical fine-grained formulation learns more comprehensive forgery localization features than multi-level localization scheme proposed in PSCC.

5.1.2 Image Editing Datasets

Tab. 3 reports IFDL results for the image editing domain. We evaluate on 5 datasets: *Columbia* [48], *Coverage* [66], *CASIA* [18], *NIST16* [2] and *IMD20* [50]. Following the previous experimental setup of [17, 26, 43, 63, 68], we pre-train the model on our proposed HiFi-IFDL and then fine-tune the pre-trained model on the *NIST16*, *Coverage* and *CASIA*. We also report the performance of HiFi-Net pre-trained on the same dataset as [43]. Tab. 3a reports the pre-trained model performance, in which our method achieves the best average performance. The ObjectFormer [63] adopts the powerful transformer-based architecture and solely specializes in forgery detection of the image editing domain, nevertheless its performance are on-par

<i>Metric: IoU / PBCA</i>		<i>Metric: AUC/PBCA</i>	
Att.Xcc. [62]	0.401/0.786	Att.Xcc. [62]	99.69/88.44
Ours	0.411/0.801	Ours	99.45/88.50

(a) localization

(b) detection

Table 4. IFDL results on DFFD dataset. [Key: **Best**]

with ours. In the fine-tune stage, our method achieves the best performance on average AUC and F1. Specifically, we only fall behind on *NIST16*, where AUC tends to saturate. We also report the image-level forgery detection results in Tab. 3c, achieving comparable results to ObjectFormer [63]. We show qualitative results in Fig. 7, where the manipulated region identified by our method can capture semantically meaningful object shape, such as the shapes of the tiger and squirrel. At last, we also offer the robustness evaluation in Tab. 2 of the supplementary, showing our performance against various image transformations.

5.1.3 Diverse Fake Face Dataset

We evaluate our method on the Diverse Fake Face Dataset (DFFD) [62]. For a fair comparison, we follow the same experiment setup and metrics: IoU and pixel-wise binary classification accuracy (PBCA) for pixel-level localization, and AUC and PBCA for image-level detection. Tab. 4 reports that our method obtains competitive performance on

	Method	Loss	Detection		Localization		
			AUC	F1	AUC	F1	
	<i>Full</i>	M,L,P	$\mathcal{L}_{cls}, \mathcal{L}_{loc}$	96.8	94.1	95.3	96.9
1	M,L,P	\mathcal{L}_{loc}	65.0	70.0	93.4	95.0	
2	M,L,P	\mathcal{L}_{cls}	95.8	92.4	66.0	58.0	
3	M,L,P	$\mathcal{L}_{cls}^4, \mathcal{L}_{loc}$	93.1	91.7	92.5	93.9	
4	M,L,P	$\mathcal{L}_{cls}^{ind}, \mathcal{L}_{loc}$	93.2	92.8	93.2	94.8	
5	M,L	$\mathcal{L}_{cls}, \mathcal{L}_{loc}$	96.6	93.0	94.8	96.0	

Table 5. Ablation study. **M**, **L**, and **P** represent the multi-branch classification module, localization module and Pconv operation, respectively. \mathcal{L}_{cls} and \mathcal{L}_{loc} are classification and localization loss, respectively. \mathcal{L}_{cls}^4 and \mathcal{L}_{cls}^{ind} denote we only perform the fine-grained classification on 4th level and classification without hierarchical path prediction. [Key: **Best**]

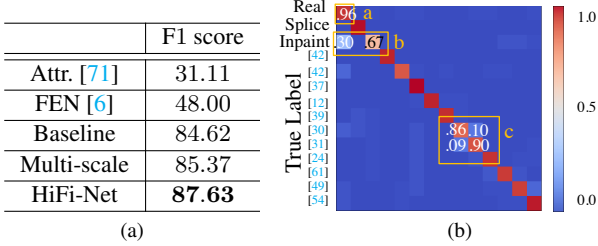


Figure 8. (a) The forgery attribute classification results. The improvement over previous works [6, 71] is because the previous works only learn to attribute CNN-synthesized images, yet do not consider attributing image editing methods. (b) The confusion matrix of forgery attribute classification at level 4, where a, b and c represent three scenarios of classification failures. The numerical value indicates the accuracy. See Sec. 5.3 and Fig. 9 for details.

detection and the best localization performance on partial-manipulated images. More results are in the appendix.

5.2. Ablation Study

In row 1 and 2 of Tab. 5, we first ablate the \mathcal{L}_{loc} and \mathcal{L}_{cls} , removing which causes large performance drops on the detection (24.1% F1) and localization (29.3% AUC), respectively. Also, removing \mathcal{L}_{cls} harms localization by 1.9% AUC and F1. This shows that fine-grained classification improves the localization, as the fine-grained classification features serve as a prior for localization. We evaluate the effectiveness of performing fine-grained classification at different hierarchical levels. In the 3th row, we only keep the 4th level fine-grained classification in the training, which causes a sensible drop of performance in detection (3.7% AUC) and localization (2.8% AUC). In the 4th row, we perform the fine-grained classification without forcing the dependency between layers of Eq. 4. This impairs the learning of hierarchical forgery attributes and causes a drop of 3.6% AUC in the detection. Lastly, we ablate the PConv in the 5th row, making model less effective for detection.

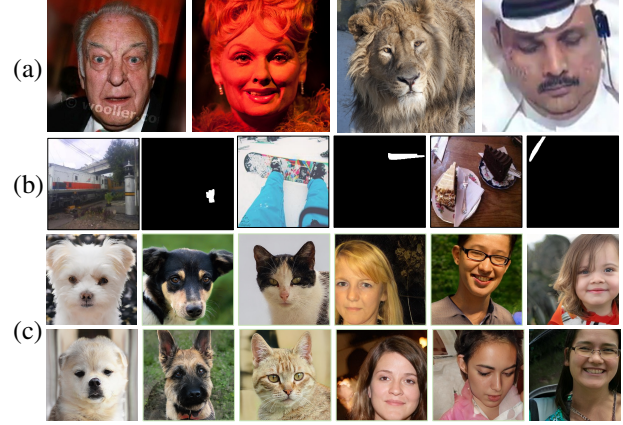


Figure 9. Three failure scenarios: (a) real images. (b) inpainting images with small removal regions. (c) images generated from different styleGANv2ada [30] and styleGANv3 [31], as shown in the last two rows, respectively.

5.3. Forgery Attribute performance

We perform the fine-grained classification among real images and 13 forgery categories on 4 different levels, and the most challenging scenario is the fine-grained classification on the 4th level. The result is reported in Tab. 8a. Specifically, we train HiFi-Net 4 times, and at each time only classifies the fine-grained forgery attributes at one level, denoted as *Baseline*. Then, we train a HiFi-Net to classify all 4 levels but without the hierarchical dependency via Eq. 4, denoted as *multi-scale*. Also, we compare to the pre-trained image attribution works [6, 71]. Also, it has been observed in Fig. 8b that we fail on 3 scenarios 1) Some real images have watermarks, extreme lightings, and distortion. 2) Inpainted images have small forgery regions. 3) styleGANv2-ada [30] and styleGAN3 [31] can produce highly similar images. Fig. 9 shows failure cases.

6. Conclusion

In this work, we develop a method for both CNN-synthesized and image editing forgery domains. We formulate the IFDL as a hierarchical fine-grained classification problem which requires the algorithm to classify the individual forgery method of given images, via predicting the entire hierarchical path. Also, HiFi-IFDL dataset is proposed to further help the community in developing forgery detection algorithms.

Limitation Please refer to the supplementary Sec. 2: the model that performs well on the conventional image editing can generalize poorly on diffusion-based inpainting method. Secondly, we think it is possible improve the IFDL learning via the larger forgery dataset.

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